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Exceedance probability analysis: a practical and effective alternative to *t*-tests

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ABSTRACT
This paper presents a practical and effective alternative to the traditional *t*-tests for (1) comparing a sample or sample mean against a known mean (i.e. one-sample test) and (2) comparing two samples or two sample means (i.e. two-sample test). The proposed method is referred to as exceedance probability (EP) analysis. In a one-sample test, EP is defined as the probability that a sample or sample mean is greater than a known mean. In a two-sample test, EP is defined as the probability that the difference between two samples or between two sample means is greater than a specified value (referred to as probabilistic effect size (PES)). This paper also defines a new statistic called relative mean effect size (RMES). RMES provides a true measure of the scientific significance (not the statistical significance) of the difference between two means. A case study of preference between two manufacturers is presented to demonstrate the effectiveness of the proposed EP analysis, compared with four existing methods: *t*-tests, common language (CL) effect size analysis, signal content index (SCI) analysis, and Bayesian analysis. Unlike these existing methods that require the assumption of normality, the proposed EP analysis can be performed with any type of distributions. The case study example is examined with a normal distribution model and a raised cosine distribution model. The former is solved with an analytical solution and the latter is solved with a numerical method known as probability domain simulation (PDS).

Keywords: alternative to *t*-tests, comparison of samples, effect size, exceedance probability

1. Introduction

There has been a long-standing debate about the validity of *t*-tests (or significance testing in general) and the associated *p*-values in the statistics community. Unlike many statistics textbooks in which *t*-tests and *t*-distribution are part of standard materials, Matloff (2014a) deliberately excludes *t*-tests and *t*-distribution in his textbook. An international journal: *Basic and Applied Social Psychology* (BASP) has officially banned significance testing from BASP since 2015 (Trafimow and Marks 2015). The American Statistician Association (ASA) made an official statement about statistical significance and *p*-values (Wasserstein and Lazar 2016). Some authors suggested retiring or abandoning statistical significance and *p*-values (e.g. Amrhein et al. 2019, McShane et al. 2018, Halsey 2019, Wasserstein et al. 2019).

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It seems that "the reign of the *p*-value is over." Then, an important question is, "what alternative analyses could we employ to fill the power vacuum?" (Halsey 2019). Trafimow and Marks (2015), the editors of BASP, stated, "… BASP will require strong descriptive statistics, including effect sizes." Huang (2020a) recently presented a new statistic that is referred to as signal content index (SCI), based on the law of conservation of energy. SCI is defined as the ratio between the signal energy and the total energy of signal and noise contained in the observed values (data). The analysis of the SCI for the difference between two means provides an alternative to the traditional *t*-tests. However, the SCI is a function of the *t* statistic. A SCI value can be converted to a *p*-value produced by a *t*-test and vice versa. In addition, like a *p*-value, the SCI is not an absolute measure of the difference between two means. It is similar to the heterogeneity index I^2 that is not an absolute measure of the heterogeneity between studies in meta-analysis.

The mathematical basis of *t*-tests is the *t*-distribution. The *t* statistic is a transformed quantity, i.e. the ratio between the sample error and sample standard deviation. The *t*-transformation itself is mathematically valid, and so is the *t*-distribution (Huang 2020b). However, the use of *t*-distribution for statistical inference may be invalid because of the *t*-transformation distortion (Huang 2018a). The *t*-transformation distortion is the root cause of extremely high *t*-scores when the sample size is very small (Huang 2018b). The *t*-based uncertainty is actually misused in measurement uncertainty analysis (Huang 2018c). D'Agostini (1998) also casted doubt on the use of the *t*-distribution as the "standard way" for handling small samples. Matloff (2014b) stated, in his blog post titled "Why are we still teaching *t*-tests?", "The *t*-test is an exemplar for the curricular ills in three separate senses ... I advocate skipping the *t*-distribution, and going directly to inference based on the Central Limit Theorem." Huang (2019) initiated a discussion with an analogous title "Why are we still teaching *t*-distribution?" on ResearchGate, suggesting to revisit all *t*-based inferences that may be problematic due to the *t*-transformation distortion.

This paper proposes a practical and effective alternative to the traditional *t*-tests, referred to as exceedance probability (EP) analysis. The concept of EP is not new; it has been used in some engineering applications such as environment protection. However, EP seems less known in statistical or scientific inference, although EP may be implicit in statistical significance tests such as *t*-tests. We focus on two tests that are often encountered in practice, (1) one-sample test: comparing a sample or sample mean against a known mean, and (2) two-sample test: comparing two samples (groups) or two sample means.

In the following sections, section 2 briefly reviews the concept of EP. Section 3 deals with one-sample tests. Section 4 deals with two-sample tests. Section 5 presents discussion. Section 6 presents a case study: preference between two manufacturers, comparing the proposed EP analysis with four existing methods: *t*-tests, common language effect size (CL) analysis, signal content index (SCI) analysis, and Bayesian analysis. Section 7 discusses the case study example with the assumption of non-normal distributions, which is solved with a numerical method. Section 8 presents conclusion and recommendation.

2. The concept of exceedance probability (EP)

Consider a random variable *X* that has a continuous probability density function (PDF) $p(x|\boldsymbol{\theta})$ with the support (-∞, +∞) (or other support), where $\boldsymbol{\theta}$ is a vector of parameters. For a normal distribution, $\boldsymbol{\theta} = (\mu, \sigma)$, where μ is the mean and σ is the standard deviation.

Exceedance probability (EP) is defined as the probability that a specified value (or limit), denoted by x_{EP}, is exceeded. That is

$$\mathrm{EP}(x_{\mathrm{EP}}) = \Pr(X > x_{\mathrm{EP}}) = \int_{x_{\mathrm{EP}}}^{\infty} p(x|\boldsymbol{\theta})dx = 1 - \Pr(X \le x_{\mathrm{EP}}) \quad (1)$$

For example, x_{90} is equal to the value, if randomly drawing a huge number of samples thorough Monte Carlo simulation from the probability distribution of X, where 10% of the samples will be below x_{90} and 90% will be above x_{90}. For symmetrical distributions such as a normal distribution, x_{50} is equivalent to the mean value. In addition, if we specify $x_{\mathrm{EP}} = 0$, EP(0) is the probability that the values of x are greater than 0.

When the model parameters $\boldsymbol{\theta}$ are known, $\mathrm{EP}(x_{\mathrm{EP}})$ will be exact according to Eq. (1). When the model parameters $\boldsymbol{\theta}$ are unknown, $\boldsymbol{\theta}$ are replaced with their estimator $\hat{\boldsymbol{\theta}}$. Then, Eq. (1) becomes

$$\widehat{\mathrm{EP}}(x_{\mathrm{EP}}) = \int_{x_{\mathrm{EP}}}^{\infty} p(x|\hat{\boldsymbol{\theta}})dx \quad (2)$$

where $p(x|\hat{\boldsymbol{\theta}})$ is the estimated PDF of X and $\widehat{\mathrm{EP}}(x_{\mathrm{EP}})$ is the estimated EP. For a normal distribution, $\hat{\boldsymbol{\theta}} = (\hat{\mu}, \hat{\sigma})$, where $\hat{\mu}$ is an estimator of μ and $\hat{\sigma}$ is an estimator of σ.

The concept of EP has been used in some engineering fields. For example, EP analysis is a standard practice for assessing the quality of receiving water. This is because water quality criteria are usually set in terms of a concentration level with the associated EP (or return period that can be converted to EP) (Huang and Fergen 1995). U.S. EPA (Environment protection agency) (1991) sets EP=0.0037 for chronic toxics to protect aquatic life. Di Toro (1984) performed EP analysis for stream quality due to runoff. Huang and Fergen (1995) performed EP analysis for BOD and DO concentration along a river due to a point load. EP analysis is also used to assesse the exposure level in a work environment (Krishnamoorthy et al. 2007).

As mentioned in the introduction section, EP seems less known in statistical or scientific inference. However, EP may be implicit in statistical significance tests such as *t*-tests. In the author's opinion, EP analysis is more straightforward, more informative, and easier to understand than *t*-tests and the associated *p*-values.

3. One-sample tests

Suppose that a sample (dataset) X=$\{x_1, x_2, \ldots, x_n\}$ is randomly drawn from a normal distribution $X \sim N(\mu, \sigma)$. Neither μ nor σ is known. The dataset gives the sample mean $\bar{x}_D$ and sample standard deviation s_D ("D" means that the sample statistic $\bar{x}$ or s is conditioned on the dataset). We are interested in two problems: (a) assessing a sample X against a known mean μ_0, and (b) assessing the sample mean $\bar{X}$ against μ_0.

In our analysis, the location parameter μ is estimated with $\bar{x}_D$ and the scale parameter σ is estimated with $s_D/c_{4,n}$, where $c_{4,n}$ is the bias correction factor that depends on the number of observations (i.e. the sample size n). Accordingly, $X: N(\bar{x}_D, \frac{s_D}{c_{4,n}})$ is the estimated probability distribution function (PDF) of $X: N(\mu, \sigma)$, given the dataset.

For problem (a), the difference between the sample X and the known mean μ_0 is defined as the effect size: $\Delta X = X - \mu_0$. ΔX is a random variable because X is a random variable. We are

interested in the probability that $\Delta X > 0$, or $X > \mu_0$, i.e. the exceedance probability (EP) of X against μ_0, denoted by $\mathrm{EP}_a(\mu_0)$. It is written as

$$\mathrm{EP}_a(\mu_0) = \Pr(\Delta X > 0) = \Pr(X > \mu_0) = 1 - \Pr(X \le \mu_0) \quad (3)$$

As a numerical example, assume that $\bar{x}_D = 20$, $\frac{s_D}{c_{4,n}}$=5, and n=25. Then, $\mathrm{EP}_a(\mu_0)$ is 25% at $\mu_0 = 23.372$, 50% at $\mu_0 = \bar{x}_D = 20$, and 75% at $\mu_0 = 16.628$. Thus, $\mathrm{EP}_a(\mu_0)$ provides a probabilistic measure for assessing X against μ_0, or a probabilistic assessment of the effect size $\Delta X = X - \mu_0$.

Note that the scale parameter in the PDF $X: N(\bar{x}_D, \frac{s_D}{c_{4,n}})$ is only a weak function of the sample size n because $c_{4,n}$ approaches unity quickly with increasing n, say n>10. Therefore, $\mathrm{EP}_a(\mu_0)$ is nearly independent of n.

For problem (b), the difference between the sample mean $\bar{X}$ and μ_0 is defined as the effect size: $\Delta\bar{X} = \bar{X} - \mu_0$. Similar to problem (a), the EP of $\bar{X}$ against μ_0, denoted by $\mathrm{EP}_b(\mu_0)$, is written as

$$\mathrm{EP}_b(\mu_0) = \Pr(\Delta\bar{X} > 0) = \Pr(\bar{X} > \mu_0) = 1 - \Pr(\bar{X} \le \mu_0) \quad (4)$$

The estimated PDF of the sample mean is $\bar{X}: N(\bar{x}_D, \frac{s_D}{c_{4,n}\sqrt{n}})$, given the dataset.

For the same assumed values: $\bar{x}_D = 20$, $\frac{s_D}{c_{4,n}}$=5, and n=25, $\mathrm{EP}_b(\mu_0)$ is 25% at $\mu_0 = 20.674$, 50% at $\mu_0 = \bar{x}_D = 20$, and 75% at $\mu_0 = 19.326$. Thus, $\mathrm{EP}_b(\mu_0)$ provides a probabilistic measure for assessing $\bar{X}$ against μ_0 or a probabilistic assessment of the effect size $\Delta\bar{X} = \bar{X} - \mu_0$.

Note that the scale parameter in the PDF $\bar{X}: N(\bar{x}_D, \frac{s_D}{c_{4,n}\sqrt{n}})$ is a function of the sample size n, so $\mathrm{EP}_b(\mu_0)$ depends on n. Also note that, in general, $\mathrm{EP}_a(\mu_0) \neq \mathrm{EP}_b(\mu_0)$. However, they take the same value, 50%, at $\mu_0 = \bar{x}_D$. That is $\mathrm{EP}_a(\bar{x}_D) = \mathrm{EP}_b(\bar{x}_D) = 50\%$.

In addition, we define the ratio between $\bar{x}_D - \mu_0$ and μ_0 as the relative mean effect size (RMES) of a one-sample test

$$\mathrm{RMES}_{\mathrm{one-sample}} = \frac{\bar{x}_D - \mu_0}{\mu_0} \quad (5)$$

$\mathrm{RMES}_{\mathrm{one-sample}}$ provides a true measure of the scientific significance (not the statistical significance) of the difference between the two means. Importantly, RMES does not depend on the sample size n.

4. Two-sample tests

Suppose that two samples (datadests) X_1={$x_{1,1}$, $x_{1,2}$, ..., $x_{1,n1}$} and X_2={$x_{2,1}$, $x_{2,2}$, ..., $x_{2,n2}$} are randomly drawn from two independent normal distributions $X_1 \sim N(\mu_1, \sigma_1)$ and $X_2 \sim N(\mu_2, \sigma_2)$, respectively. Neither μ_1 nor μ_2 is known, neither σ_1 nor σ_2 is known, and in general $\sigma_1 \neq \sigma_2$. The two datasets give the sample means $\bar{x}_{1,D}$ and $\bar{x}_{2,D}$, and sample standard deviations $s_{1,D}$ and $s_{2,D}$, respectively. The sample sizes are n_1 and n_2 respectively. Again, we are interested in two problems:

(a) assessing the difference between the two samples X_1 and X_2, and (b) assessing the difference between the two sample means $\bar{X}_1$ and $\bar{X}_2$.

Similar to the analysis in the one-sample test, the estimated PDFs of X_1 and X_2 are $X_1: N(\bar{x}_{1,D}, \frac{s_{1,D}}{c_{4,n1}}) \approx X_1: N(\mu_1, \sigma_1)$ and $X_2: N(\bar{x}_{2,D}, \frac{s_{2,D}}{c_{4,n2}}) \approx X_2: N(\mu_2, \sigma_2)$, respectively.

For problem (a), the difference between X_1 and X_2 is defined as the effect size: $\Delta X = X_1 - X_2$. ΔX is a random variable because X_1 and X_2 are random variables. The estimated PDF of ΔX is also normal and is written as

$$p(\Delta X) = N\left(\left(\bar{x}_{1,D} - \bar{x}_{2,D}\right), \sqrt{\left(\frac{s_{1,D}}{c_{4,n1}}\right)^2 + \left(\frac{s_{2,D}}{c_{4,n2}}\right)^2}\right) \tag{6}$$

We are interested in the probability that $\Delta X > 0$, or $X_1 > X_2$, i.e. the EP of ΔX against 0, denoted by $\mathrm{EP}_a(0)$. It is written as

$$\mathrm{EP}_a(0) = \Pr(\Delta X > 0) = \Pr(X_1 > X_2) \tag{7}$$

$\mathrm{EP}_a(0)$ is the estimated probability that the sample X_1 from one distribution (or group) is greater than the sample X_2 from another distribution (or group). The meaning of $\mathrm{EP}_a(0)$ is clear without any confusion; even a person without statistical training can understand it.

Furthermore, we define the EP of ΔX against a specified value Δx_{EP} as

$$\mathrm{EP}_a(\Delta x_{\mathrm{EP}}) = \Pr(\Delta X > \Delta x_{\mathrm{EP}}) = 1 - \Pr(\Delta X \leq \Delta x_{\mathrm{EP}}) \tag{8}$$

Note that $\mathrm{EP}_a(0)$ is a special case where $\Delta x_{\mathrm{EP}} = 0$.

Because the distribution of ΔX is symmetric, $\mathrm{EP}_a(\Delta x_{50} = \bar{x}_{1,D} - \bar{x}_{2,D})$ means that 50% of the Δx samples will be greater than Δx_{50}. In other words, X_1 is greater (or smaller) than X_2 by Δx_{50} at the odds of 1:1. On the other hand, $\mathrm{EP}_a(\Delta x_{75})$ means that 75% of the Δx samples will be greater than Δx_{75}, or X_1 is greater than X_2 by Δx_{75} at the odds of 3:1. Thus, Δx_{EP} provides a probabilistic measure of the effect size $\Delta X = X_1 - X_2$. It is therefore referred to as the probabilistic effect size (PES).

Note that the scale parameter in $p(\Delta X)$ is only a weak function of the sample sizes n_1 and n_2 because $c_{4,n}$ approaches unity quickly with increasing n, say n>10. Therefore, $\mathrm{EP}_a(0)$ or $\mathrm{EP}_a(\Delta x_{\mathrm{EP}})$ is nearly independent of the sample sizes n_1 and n_2.

For problem (b), the difference between the two sample means $\bar{X}_1$ and $\bar{X}_2$ is defined as the effect size: $\Delta \bar{X} = \bar{X}_1 - \bar{X}_2$. The estimated PDF of $\Delta \bar{X}$ is also normal and is written as

$$p(\Delta \bar{X}) = N\left(\left(\bar{x}_{1,D} - \bar{x}_{2,D}\right), \sqrt{\left(\frac{s_{1,D}}{c_{4,n_1}\sqrt{n_1}}\right)^2 + \left(\frac{s_{2,D}}{c_{4,n_2}\sqrt{n_2}}\right)^2}\right) \tag{9}$$

Similar to problem (a), the EP of $\Delta \bar{X}$ agaianst 0 (i.e. $\bar{X}_1 > \bar{X}_2$), denoted by $\mathrm{EP}_b(0)$, is written as

$$\mathrm{EP}_b(0) = \Pr(\Delta\bar{X} > 0) = \Pr(\bar{X}_1 > \bar{X}_2) \tag{10}$$

Also similarly, the EP of $\Delta\bar{X}$ against a specified value $\Delta\bar{x}_{\mathrm{EP}}$ is written as

$$\mathrm{EP}_b(\Delta\bar{x}_{\mathrm{EP}}) = \Pr(\Delta\bar{X} > \Delta\bar{x}_{\mathrm{EP}}) = 1 - \Pr(\Delta\bar{X} \le \Delta\bar{x}_{\mathrm{EP}}) \tag{11}$$

Analogously, $\Delta\bar{x}_{\mathrm{EP}}$ provides a probabilistic measure of the effect size $\Delta\bar{X} = \bar{X}_1 - \bar{X}_2$. Accordingly, $\Delta\bar{x}_{\mathrm{EP}}$ is also a probabilistic effect size (PES). We have $\Delta\bar{x}_{50} = \Delta x_{50} = \bar{x}_{1,D} - \bar{x}_{2,D}$.

Note that the scale parameter in $p(\Delta\bar{X})$ is a function of the sample sizes n_1 and n_2. Therefore, $\mathrm{EP}_b(0)$ and $\mathrm{EP}_b(\Delta\bar{x}_{\mathrm{EP}})$ depend on the sample sizes n_1 and n_2. Also note that, in general, $\mathrm{EP}_a(\Delta x_{\mathrm{EP}}) \neq \mathrm{EP}_b(\Delta\bar{x}_{\mathrm{EP}})$, except that both are 50% at $\Delta x_{50} = \Delta\bar{x}_{50} = \bar{x}_{1,D} - \bar{x}_{2,D}$.

In addition, we define the ratio between Δx_{50} (or $\Delta\bar{x}_{50}$) and a weighted-average of the two sample means as the relative mean effect size (RMES) of a two-sample test

$$\mathrm{RMES}_{\mathrm{two-sample}} = \frac{\bar{x}_{1,D} - \bar{x}_{2,D}}{\bar{x}_w} \tag{12}$$

where $\bar{x}_w$ may be calculated as the inverse-variance weighted-average

$$\bar{x}_w = \frac{\dfrac{n_1\bar{x}_{1,D}}{s_{1,\mathrm{D}}^2} + \dfrac{n_2\bar{x}_{2,D}}{s_{2,\mathrm{D}}^2}}{\dfrac{n_1}{s_{1,\mathrm{D}}^2} + \dfrac{n_2}{s_{2,\mathrm{D}}^2}} \tag{13}$$

$\mathrm{RMES}_{\mathrm{two-sample}}$ provides a true measure of the scientific significance (not the statistical significance) of the difference between two sample means. Note that if $s_{2,\mathrm{D}}^2/n_2$ goes to zero, $\mathrm{RMES}_{\mathrm{two-sample}}$ reduces to $\mathrm{RMES}_{\mathrm{one-sample}}$, where $\bar{x}_{D,1}$ is replaced by $\bar{x}_D$ and $\bar{x}_{2,D}$ is replaced by μ_0.

It should be pointed out that EP analysis does not require the assumption of normality. The PDF of X in a one-sample test, or the PDFs of X_1 and X_2 in a two-sample test can be any type of distributions. For example, X_1 can be normally distributed and X_2 can be uniformly distributed; Eqs. (7) and (8) still apply. However, in this situation, a numerical procedure may be required to generate a solution. A numerical method known as probability domain simulation (PDS) is described in Appendix. The use of PDS for a case study example is presented later in this paper.

5. Discussion

5.1. Comparison with the analysis of common language (CL) effect size

In the problem (a) of two-sample tests, the EP of ΔX against zero, i.e. $\mathrm{EP}_a(0) = \Pr(X_1 > X_2)$, is the probability that the sample X_1 from one distribution (or group) is greater than the sample X_2 from another distribution (or group). Thus, the meaning of $\mathrm{EP}_a(0)$ is the same as the meaning of

an effect size statistic called common language (CL) effect size proposed by McGraw and Wong (1992). CL may be under other names such as the probability of superiority (PS), area under the receiver operating characteristic (AUC), or A for its nonparametric version (Ruscio and Mullen 2012). However, the formula of $\mathrm{EP}_a(0)$ is different from the formula of CL. $\mathrm{EP}_a(0)$ is calculated based on the estimated PDF of ΔX, Eq. (6); it does not require the assumption of normality. In principle, $\mathrm{EP}_a(0)$ can be calculated from the difference between two distributions of any type. In contrast, the calculation of CL requires the assumption of normality. CL is calculated based on the standardized mean effect size that is equivalent to a 'z-score' of a standard normal distribution (Coe 2002). For two independent samples, the z-score for CL is written as (Coe 2002)

$$z_{\mathrm{CL}} = \frac{\bar{x}_{1,D} - \bar{x}_{2,D}}{\sqrt{s_{1,D}^2 + s_{2,D}^2}} \tag{14}$$

Therefore, CL is the upper tail probability associated with z_{CL} on a table of the normal cumulative distribution. Note that z_{CL} is different from the usual z-score for a z-test, in which the standard error, e.g. $s_1/\sqrt{n_1}$, is used, instead of the sample standard deviation s_1.

If both X_1 and X_2 are normally distributed, and the variances σ_1^2 and σ_2^2 are known or the sample sizes n_1 and n_2 are very large, the numerical value of $\mathrm{EP}_a(0)$ will be the same or approximately the same as CL. If $s_{1,D}^2$ and $s_{2,D}^2$ are estimated with small samples, $\mathrm{EP}_a(0)$ will be slightly different from CL. This can be seen in the case study example presented later in this paper.

5.2. Comparison with the *z*-test and *t*-test

It is important to note that the z-test or t-test and the associated p-value only apply to problem (b). They do not apply to problem (a). Therefore the following discussion addresses problem (b) only.

There is a relationship between $\mathrm{EP}_b(\mu_0)$ and the one-tailed p-value produced by a one-sample z-test or t-test; there is also a relationship between $\mathrm{EP}_b(0)$ and the one-tailed p-value produced by a two-sample z-test or t-test.

For a one-sample z-test, the one-tailed p-value for the null: the effect is greater than zero, can be calculated as

$$p_{\mathrm{one-tailed}} = \Pr\left(\left[z = \frac{\bar{X} - \bar{x}_D}{\frac{\sigma}{\sqrt{n}}}\right] < \left[-z_p = -\frac{\bar{x}_D - \mu_0}{\frac{\sigma}{\sqrt{n}}}\right]\right) = \Pr(\bar{X} < \mu_0) = 1 - \mathrm{EP}_b(\mu_0) \tag{15}$$

For a two-sample equal-variance z-test, the one-tailed p-value for the null: the effect is greater than zero, can be calculated as

$$\begin{aligned} p_{\mathrm{one-tailed}} &= \Pr\left(\left[z = \frac{(\bar{X}_1 - \bar{X}_2) - (\bar{x}_{1,D} - \bar{x}_{2,D})}{\sigma\sqrt{\frac{1}{n_1} + \frac{1}{n_2}}}\right] < \left[-z_p = -\frac{\bar{x}_{1,D} - \bar{x}_{2,D}}{\sigma\sqrt{\frac{1}{n_1} + \frac{1}{n_2}}}\right]\right) \\ &= \Pr\big((\bar{X}_1 - \bar{X}_2) < 0\big) = \Pr(\bar{X}_1 < \bar{X}_2) = 1 - \mathrm{EP}_b(0) \end{aligned} \tag{16}$$

Since the *t*-test approaches the *z*-test when the sample size is large (say, n>30), the *p*-value produced by a one-tailed *t*-test will be approximately equal to $1 - \mathrm{EP}_b(\mu_0)$ for the one-sample test and will be approximately equal to $1 - \mathrm{EP}_b(0)$ for the two-sample test.

The EP analysis for problem (b) is superior to the one-tailed *t*-test. First, $\mathrm{EP}_b(\mu_0)$ or $\mathrm{EP}_b(0)$ has a clear meaning without any confusion. For example, $\mathrm{EP}_b(0) = \Pr(\bar{X}_1 > \bar{X}_2)$ is the estimated probability that the sample mean $\bar{X}_1$ from one distribution (or group) is greater than the sample mean $\bar{X}_2$ from another distribution (or group). A person even not trained in statistics can understand this statement. $\mathrm{EP}_b(\mu_0)$ or $\mathrm{EP}_b(0)$ provides a probabilistic assessment about the effect size $\bar{X}_1 - \bar{X}_2$. In other words, EP analysis answers the question: "how likely is the difference between $\bar{X}_1$ and $\bar{X}_2$?" However, like the *p*-value, $\mathrm{EP}_b(\mu_0)$ or $\mathrm{EP}_b(0)$ does not provide an absolute measure of the effect size. We therefore do not recommend using any cut-off value of $\mathrm{EP}_b(\mu_0)$ or $\mathrm{EP}_b(0)$ to assesse statistical significance. We even do not recommend using the term "statistical significance" in EP analysis. Instead, we suggest using $\mathrm{EP}_b(\mu_0)$ or $\mathrm{EP}_b(0)$ in conjunction with RMES for scientific inference. RMES answers the question: "how much is the difference between $\bar{X}_1$ and $\bar{X}_2$?" In contrast, the meaning of *p*-values is often misinterpreted or misunderstood. In particular, statisticians tend to interpret evidence dichotomously based on whether or not a *p*-value crosses the conventional 0.05 threshold for statistical significance (McShane and Gal 2017). For example, p>0.05 is often misinterpreted as "the probability that the null hypothesis is true" or "p>0.05 means that no effect was observed." However, statistical significance is not the same as scientific significance. Moreover, since the *p*-value decreases as the sample size increases, and approaches zero as sample size goes to infinity, statistical significance can be always achieved with a sufficiently large sample in *t*-tests, even if the absolute difference between two means (i.e. the effect size) or RMES is very small and meaningless.

Second, the calculation of $\mathrm{EP}_b(\mu_0)$ or $\mathrm{EP}_b(0)$ does not require the assumption of normality. It does not need to assume equal variance or use a pooled variance. In principle, EP analysis can be performed on any type of distribution. In contrast, the calculation of *p*-values in a *t*-test requires the assumption of normality. It also needs to assume equal variance or use a pooled variance. Therefore, the EP analysis for problem (b) has fewer restrictions and fewer limitations than *t*-tests; $\mathrm{EP}_b(\mu_0)$ or $\mathrm{EP}_b(0)$ is more accurate (or has less uncertainty) than *p*-values.

5.3. The Bayesian view

It should be pointed out that the proposed EP analysis is based on the frequentist view. That is, the unknown parameters μ and σ are regarded and treated as constants that are estimated with the point estimation method with the mean-unbiased criterion. In the Bayesian view, however, the unknown parameters μ and σ are treated as random variables. Huang (2022) recently presented a modified Bayesian method based on the rule of transformation between the frequentist view and Bayesian view; he demonstrated that, in the case that no prior information is involved, the frequentist sampling distribution, estimated with a given dataset, is virtually the same as the Bayesian probability distribution of the unknown parameter (e.g. μ). Huang (2022) also demonstrated that, in the light of the law of aggregation of information (LAI) (Huang 2020c) and the frequentist-Bayesian transformation rule, the frequentist and Bayesian inference are virtually equivalent, so they can be unified, at least in measurement uncertainty analysis. Therefore, EP analysis may also be performed based on the Bayesian view. Take the problem (b) of two-sample tests as an example. According to the frequentist-Bayesian transformation rule, $\bar{X}_1 \to \mu_1$, and

$\bar{X}_2 \to \mu_2$. Consequently, $\Delta\bar{X} \to \Delta\mu$, the PDF of $\Delta\mu$ is the same as Eq. (9). Furthermore, Eq. (10) and Eq. (11) also apply to $\Delta\mu$. However, the Bayesian view may not be applicable to the problem (a) of two-sample tests, which may only be dealt with by the frequentist sampling theory.

The interested reader is referred to Huang (2020c) for the law of aggregation of information (LAI) and Huang (2022) for the modified Bayesian method and the potential unification of the frequentist and Bayesian inference.

6. Case study: preference between two manufacturers

We consider a well-posted example that is originally given in a textbook of Roberts (1964). Two manufacturers, denoted by A and B, are suppliers for a component. We are concerned with the lifetime of the component and want to choose the manufacturer that affords the longer lifetime. Manufacturer A supplies 9 units for lifetime test. Manufacturer B supplies 4 units. The test data give the sample means 42 and 50 hours, and the sample standard deviations 7.48 and 6.87 hours, for the units of manufacturer A and B respectively.

Roberts (1964) discussed this example with a two-tailed *t*-test and concluded that, at the 90% level, the samples afford no significant evidence in favor of either manufacturer over the other. Jaynes (1976) discussed this example with a Bayesian analysis. He argued that our common sense tell us immediately, without any calculation, the test data constitutes fairly substantial (but not overwhelming) evidence in favor of manufacturer B. Huang (2020a) recently discussed this example with a SCI analysis.

6.1. The *t*-tests

In this study, we conducted the *t*-tests with the pooled variance and Welch's *t*-test. We performed the one-tailed and two-tailed tests. Table 1 shows the results.

Table 1. Results of the *t*-tests

	t-test with pooled variance	Welch's *t*-test
Degrees of freedom	11	6.72
t statistic	1.8436	1.9568
p-value (one-tailed)	0.0462	0.0465
p-value (two-tailed)	0.0923	0.0930

According to the dichotomous interpretation of evidence based on whether or not a *p*-value crosses the conventional 0.05 threshold for statistical significance, the estimated *p*-values from both of the two-tailed *t*-tests suggested that, at the 95% level, the samples afford no significant evidence in favor of either manufacturer over the other. On the other hand, the one-tailed *t*-tests at the 95% level barely suggest significance. It seems that the *t*-tests fail to extract evidence that is already clear to our unaided common sense that we should prefer manufacturer B.

The estimated *p*-value from a *t*-test depends on the sample sizes, or degrees of freedom. For this example, the *p*-values would be smaller if the sample sizes were greater than 9 and 4 for manufacturer A and B respectively. However, the mean effect size $\bar{x}_{A,D} - \bar{x}_{B,D}$, which is a true measure of scientific significance, does not depends on the sample sizes. While we certainly prefer large samples when making scientific inference, our decision should not be made based on the *p*-value that varies with the sample size.

6.2. The Bayesian analyses

In the Bayesian analysis of Jaynes (1976), the location parameters, i.e. the unknown mean lifetime of manufacturer A's and manufacturer B's components, are treated as random variables and are denoted by a and b respectively. Jaynes (1976) calculated the probability that $b>a$, conditioned on all available data. That is

$$\Pr(b > a) = \int_{-\infty}^{\infty} da \int_{a}^{\infty} p(a)p(b)\, db \tag{17}$$

where $p(a)$ is the posterior distribution of a, based on the sample of n=9 items supplied by manufacturer A, and $p(b)$ is the posterior distribution of b, based on the sample of n=4 items supplied by manufacturer B. By using the Jeffreys' prior, Jaynes (1976) found that $p(a)$ and $p(b)$ are the scaled and shifted t-distributions. The integration of Eq. (17) gives a probability of 92.0% or odds of 11.5:1 that manufacturer B's components have a greater mean lifetime, which conforms to the indication of common sense (Jaynes 1976).

However, the estimated probability $\Pr(b > a)$ with Eq. (17) may be questionable because of two issues in the Bayesian formulation for this example. The first problem is the use of the Jeffreys' prior. In fact, there has been a debate on the validity of Jeffreys priors among Bayesians. For example, D'Agostini (1998), a leading proponent of Bayesian methods in particle physics, argued that "…it is rarely the case that in physical situations the status of prior knowledge is equivalent to that expressed by the Jeffreys priors, …" D'Agostini further stated, "The default use of Jeffreys priors is clearly unjustified, especially in inferring the parameters of the normal distribution, …." Moreover, Huang (2018b) revealed that the scaled and shifted t-distribution is a distorted sampling distribution due to the Bayesian 'transformation'.

The second problem is that the traditional Bayes Theorem: $\text{posterior} \propto \text{prior} \times \text{likelihood}$, is actually flawed. In fact, the traditional Bayes Theorem is a reformulated form of the original Bayes Theorem. Huang (2022) demonstrated that it is faulty to use likelihood function in the reformulated Bayes Theorem. This flaw is the root cause of the inherent bias of the traditional Bayesian method.

These two problems can be solved with a new modified Bayesian method that is derived based on the law of aggregation of information (LAI) and the rule of transformation between the frequentist view and Bayesian view (Huang 2022). According to the modified Bayesian method, the posterior distribution of a is written as

$$p(a) = N(a|\bar{x}_{A,D}, \frac{s_{A,D}}{c_{4,n_A}\sqrt{n_A}}) \tag{18}$$

where c_{4,n_A}=0.9693 at n_A=9, $\bar{x}_{A,D} = 42$ hours, and $s_{A,D} = 7.48$ hours.

The posterior distribution of b is written as

$$p(b) = N(b|\bar{x}_{B,D}, \frac{s_{B,D}}{c_{4,n_B}\sqrt{n_B}}) \tag{19}$$

where c_{4,n_B}=0.9213 at n_B=4, $\bar{x}_{B,D} = 50$ hours, and $s_{B,D} = 6.87$ hours.

Substituing Eqs. (18) and (19) into Eq. (17) yields a probability of 96.7% or odds of 29.1:1

that manufacturer B's components have a greater mean lifetime.

It is important to note that, the estimated probability $\Pr(b > a)$ or odds from both of the above Bayesian analyses is only for the *mean lifetime of the samples* with n=9 and 4 for manufacturer A and B respectively; it is not for the *lifetime of individual units*. The Bayesian analysis depends on the sample sizes. The estimated probability $\Pr(b > a)$ or odds would be large if the sample sizes were large.

It should be remarked that the two-sample one-tailed *t*-test is essentially equivalent to Jaynes' Bayesian analysis. According to the discussion in subsection 4.2, $(1 - p_{\text{one-tailed}}) \approx \Pr(b > a)$. The one-tailed *t*-test using the pooled variance gives a *p*-value of 0.0462, leading to $(1 - p_{\text{one-tailed}}) \times 100 = 95.38\%$. This result is comparable to Jaynes' Bayesian analysis result $\Pr(b > a) = 92\%$.

6.3. The SCI analysis

The signal content index (SCI) for the difference between two sample means is defined as (Huang 2020a)

$$\text{SCI} = 1 - \frac{1}{(\bar{x}_1 - \bar{x}_2)^2}\left(\frac{(s_1)^2}{n_1} + \frac{(s_2)^2}{n_2}\right) \tag{20}$$

For this example, $1 \to A$ and $2 \to B$. Substituting the values that n_A=9, $\bar{x}_{A,D} = 42$ hours, $s_{A,D} = 7.48$ hours, n_B=4, $\bar{x}_{B,D} = 50$ hours, and $s_{B,D} = 6.87$ hours into Eq. (18) gives SCI=0.74. This SCI value suggests that there is substantial difference between the mean lifetimes of two manufactures' components.

In addition, Huang (2020a) defines the sample signal energy (SSE) as

$$\text{SSE} = \bar{x}^2 - \frac{s^2}{n} \tag{21}$$

For this example, the mean lifetime is the signal. The SSE values are 1758 and 2490 (hour)^2 for manufacturer A's and B's sample means respectively. That is, manufacturer B's sample mean contains significantly greater signal energy than manufacturer A's sample mean. Based on the SCI value and the SSE values, we should have a preference of manufacturer B.

However, like the *t*-tests and the Bayesian analyses, the SCI analysis also depends on the sample sizes. The SCI approaches unity when the sample sizes are very large even if the mean effect size $\bar{x}_1 - \bar{x}_2$ is small and insignificant. That is, the SCI is not an absolute measure of the effect size. Therefore, a scientific inference must consider both the SCI and SSE values.

6.4. The analysis of common language (CL) effect size

According to Eq. (14), the *z*-score z_{CL} is calculated as

$$z_{\text{CL}} = \frac{\bar{x}_{B,D} - \bar{x}_{A,D}}{\sqrt{s_{B,D}^2 + s_{A,D}^2}} = \frac{50 - 42}{\sqrt{6.87^2 + 7.84^2}} = 0.808 \tag{22}$$

The resulting CL is 0.791 (or 79.1%). That is, the lifetime of manufacturer B's components (individual units) is greater than the lifetime of manufacturer A's components (individual units) with a probability of 79.1% or at an odds of 3.8:1. According to this CL analysis, we should have a preference of manufacturer B.

6.5. The exceedance probability (EP) analysis

It is important to note again that all of the above analyses, except for the CL analysis, are for the difference between the *two sample means*: two mean lifetimes of the tested units. That is, these analyses deal with the problem (b) of two-sample tests. Indeed, *t*-tests, Bayesian analyses, and SCI analysis, apply to the problem (b) of two-sample tests only; they are not applicable to the problem (a) of two-sample tests. However, this example should be considered as a problem (a) of two-sample tests because we are more concerned about the *lifetime of all individual units* in a group than the *mean lifetime of the group*. Therefore, we conducted EP analysis for the effect size ΔX in this study.

Under the assumption of normality, the estimated PDF of manufacturer A's lifetime X_A (individual units) is written as

$$p(X_A) = N(\bar{x}_{A,D}, \frac{s_{A,D}}{c_{4,n_A}}) \tag{23}$$

The estimated PDF of manufacturer B's lifetime X_B (individual units) is written as

$$p(X_B) = N(\bar{x}_{B,D}, \frac{s_{B,D}}{c_{4,n_B}}) \tag{24}$$

Let $\Delta X = X_B - X_A$. The PDF of ΔX is estimated as

$$p(\Delta X) = N\left(\left(\bar{x}_{B,D} - \bar{x}_{A,D}\right), \sqrt{\left(\frac{s_{A,D}}{c_{4,n_A}}\right)^2 + \left(\frac{s_{B,D}}{c_{4,n_B}}\right)^2} \right) = N(8, 10.44) \tag{25}$$

The probability that manufacturer B's components (individual units) has a greater lifetime, i.e. $X_B > X_A$, is calculated as

$$\mathrm{EP}_a(0) = \Pr(X_B > X_A) = 77.8\% \tag{26}$$

In other words, the lifetime of manufacturer B's components (individual units) is greater than the lifetime of manufacturer A's components (individual units) at an odds of 3.5:1.

Note that $\mathrm{EP}_a(0) = \Pr(X_B > X_A) = 77.8\%$ and CL=79.1%. The CL value is slightly greater than the $\mathrm{EP}_a(0) = \Pr(X_B > X_A)$ value. This is because the CL calculation does not account for the negative bias of the sample standard deviation when the sample size is small.

Moreover, $\Delta x_{50} = 8$ hours and $\Delta x_{75} = 0.958$ hours. That is, the lifetime of manufacturer B's components (individual units) is greater than the lifetime of manufacturer A's components (individual units) by 8 hours at the odds of 1:1, and by 0.958 hours at the odds of 3:1. Thus, we

should have a preference of manufacturer B.

We also calculated the relative mean effect size (RMES) according to Eq. (12). The RMES is 17.79%, which indicates that the mean lifetime of manufacturer B's components is greater than the mean lifetime of manufacturer A's component by 17.79%. This RMES value is considered to be scientifically or practically significant.

7. Calculating $\mathrm{EP}_a(0)$ for the case study example with non-normal distributions

We have pointed out in section 4 that EP analysis does not require the assumption of normality. The PDFs of X_1 and X_2 in a two-sample test can be any type of distribution. If X_1 and/or X_2 are not normally distributed, however, an analytical solution of $p(\Delta X)$ may not be available so that a numerical procedure may be required. Two numerical methods may be used. One is the well-known Monte Carlo simulation (MCS) and the other is probability domain simulation (PDS). Detailed discussion on PDS and a comparison with its counterpart: sampling-domain simulation, i.e. MCS, can be found in Huang and Fergen (1995). Appendix briefly describes the PDS for a two-dimensional problem.

In this section, we consider the case study example again, but assume that the lifetime of a manufacturer's component follows a raised cosine distribution. We present the PDS results for $\mathrm{EP}_a(0)$ to demonstrate the effectiveness of PDS for the EP analysis with non-normal distributions.

According to Castrup (2004), the PDF of a raised cosine distribution centered at zero is written as

$$p(x) = \begin{cases} \frac{1}{2\alpha}\left[1 + \cos\frac{\pi x}{\alpha}\right] & -\alpha \le x < +\alpha \\ 0 & \text{elsewhere} \end{cases} \tag{27}$$

where α is the bounding limit.

The standard deviation, denoted by σ, of the raised cosine distribution is written as (Castrup 2004)

$$\sigma = \frac{\alpha}{\sqrt{3}}\sqrt{1 - \frac{6}{\pi^2}} = 0.3615\alpha \tag{28}$$

Castrup (2004) discussed four candidate distributions with finite bounding limits for a measurand (or for a calibration error): uniform, triangular, quadratic, and raised cosine. Castrup (2004) commented that the uniform distribution is not appropriate because it is not a physically credible distribution. The triangular distribution is not appropriate either because it displays abrupt transitions at the bounding limits and at the center, which are physically unrealistic. The quadratic distribution does not have a discontinuity at the center, but it rises abruptly at the bounding limits, which diminishes its physical validity. The raised cosine distribution overcomes all shortcomings of the other three distributions; it exhibits a central tendency and can be determined from minimum containment limits (Castrup 2004). Moreover, the shape of a raised cosine distribution looks similar to the shape of a normal distribution except that it has finite bounding limits. In fact, a raised cosine distribution is more reasonable than a normal distribution for describing a measurand (or calibration error) with finite bounding limits. A normal distribution has infinitely long tails

that are physically unrealistic for the component lifetime of a manufacturer because the component lifetime must have a lower and an upper limit due to the quality control program at the manufacturer. However, a raised cosine distribution is not as mathematically convenient as a normal distribution; it may not lead to an analytical solution in the EP analysis.

The lifetime of manufacturer A's component is centered at $x=\bar{x}_{A,D}$ and is within the interval between the lower limit $\bar{x}_{A,D}-\alpha_A$ and the upper limit $\bar{x}_{A,D}+\alpha_A$. According to Eq. (27), its PDF can be written as

$$p(x_A)=\begin{cases}\frac{1}{2\alpha_A}\left[1+\cos\frac{\pi(x_A-\bar{x}_{A,D})}{\alpha_A}\right] & \left(\bar{x}_{A,D}-\alpha_A\right)\le x_A<(\bar{x}_{A,D}+\alpha_A)\\ 0 & \text{elsewhere}\end{cases} \tag{29}$$

In order to be compatible with the normal distribution, we assume that $\sigma_A=s_{A,D}/c_4$. Thus, $\alpha_A=s_{A,D}/(0.3615c_4)$=21.35 hours.

Similarly, the PDF for the lifetime of manufacturer B's component is centered at $x=\bar{x}_{B,D}$with the lower and upper limits $\bar{x}_{B,D}-\alpha_B$ and $\bar{x}_{B,D}+\alpha_B$ respectively. It is written as

$$p(x_B)=\begin{cases}\frac{1}{2\alpha_B}\left[1+\cos\frac{\pi(x_B-\bar{x}_{B,D})}{\alpha_B}\right] & \left(\bar{x}_{B,D}-\alpha_B\right)\le x_B<(\bar{x}_{B,D}+\alpha_B)\\ 0 & \text{elsewhere}\end{cases} \tag{30}$$

where $\alpha_B=s_{B,D}/(0.3615c_4)$=19.46 hours.

Table 2 summaries the parameter values for the raised cosine distributions of the lifetime of two manufacturers' components.

Table 2. Parameter values for the raised cosine distributions (units: hours)

Manufacturer	Center	Bounding limit	Lower limit	Upper limit
A	42	21.35	20.65	63.35
B	50	19.46	30.54	69.46

We implemented the two-dimensional PDS using an Excel spreadsheet. The range of *x* is divided into *m*=100 intervals. Thus, $\Delta x_A=0.4270$ and $\Delta x_B=0.3892$.

We are interested in $\mathrm{EP}_a(0)=\Pr(\Delta X>0)=\Pr(X_B>X_A)$ only. The resulting $\mathrm{EP}_a(0)$ from the PDS with the raised cosine distributions is 77.1%. This value is compatible with $\mathrm{EP}_a(0)=77.8\%$ obtained from the analytical solution with the normal distributions.

8. Conclusion and recommendation

The proposed exceedance probability (EP) analysis provides a probabilistic assessment of the effect size (e.g. the difference between two samples or two means). The meaning of EP is clear without any confusion; a person even not trained in statistics can understand it. EP analysis, in conjunction with the proposed relative mean effect size (RMES), provides the basis for scientific inference.

The EP analysis for the problem (a) of two-sample tests under the assumption of normality is essentially the same as the CL (common language effect size) analysis. The EP analysis for the

problem (b) of two-sample tests is essentially the same as a one-tailed *z*-test when the population standard deviations are known; it is approximately equal to the one-tailed *t*-test. However, EP analysis is more straightforward, more informative, and easier to understand than the *t*-test and the associated *p*-value. Moreover, unlike the CL analysis, *z*-tests, or *t*-tests, EP analysis does not require the assumption of normality. In principle, EP analysis can be performed on any type of distribution. In addition, the calculation of EP does not need to assume equal variance or use a pooled variance. Therefore, EP analysis has fewer restrictions or fewer limitations, and more accurate (or has less uncertainty) than either the CL analysis or *t*-tests.

In the author's opinion, problem (a) is more meaningful than problem (b) in many real-world applications. However, the *t*-test and the associated *p*-value are applicable to problem (b) only. The *p*-value, which depends on the sample sizes, is misleading in statistical and scientific inference, because "significance", in terms of the conventional 0.05 threshold, can be always achieved with a sufficiently large sample, even if the absolute difference between two means (i.e. the effect size) or RMES is very small and meaningless. Therefore, we suggest considering problem (a) whenever it applies and always reporting RMES. We do not recommend any threshold in EP analysis. We even do not recommend using the term "statistical significance" in EP analysis.

When dealing with non-normal distributions, two numerical methods may be used for EP analysis: Monte Carlo simulation (MCS) and probability domain simulation (PDS). The case study of preference between two manufacturers has demonstrated the effectiveness of PDS with non-normal distributions.

Appendix: Probability domain simulation (PDS)

Consider a random quantity Z that relates to a random vector $\mathbf{X}$ in a general form

$$Z = f(\mathbf{X}) \tag{31}$$

where $\mathbf{X} = (X_1, X_2, \ldots \ldots X_n,)$ and n is the number of input quantities. n is also referred to as the dimension of the problem.

PDS is based on the following proposition: for any value z of Z, the probability of P(Z=z) is equal to the sum of all probabilities that all [$\mathbf{x}$] of [$\mathbf{X}$] satisfy $z = f(\mathbf{x})$ (Huang and Fergen 1995). This proposition is an extension of the proposition for two special cases: $Z = X + Y$ and $Z = X/Y$ discussed in Berman (1969). The proposition can be demonstrated with the law of total probability and a rule for combining the number of ways in which events can occur (e.g. Huntsberger 1970).

We illustrate the algorithm of PDS, based on the proposition, for a two-dimensional problem $\mathbf{X} = (X_1, X_2)$ and $Z = f(X_1, X_2)$. We assume that X_1 and X_2 are independent random variables having PDFs $p_1(x_1)$ and $p_2(x_2)$ respectively. The ranges of x_1 and x_2 are divided into m intervals of Δx_1 and Δx_2, respectively. Let $x'_{1,i}$ denote the realization of X_1 within the interval $(x_{1,i} - \frac{\Delta x_1}{2}, x_{1,i} + \frac{\Delta x_1}{2})$, and analogously for $x'_{2,j}$. The output of $Z = f(X_1, X_2)$ at $X_1 = x'_{1,i}$ and $X_2 = x'_{2,j}$, denoted by $z_{i,j}$, is written as

$$z_{i,j} = f(x'_{1,i}, x'_{2,j}) \tag{32}$$

The occurrence probability of $z_{i,j}$ is the probability that $x'_{1,i}$ and $x'_{2,j}$ occur simultaneously. It is written as

$$P(z_{i,j}) = P_1(x'_{1,i})P_2(x'_{2,j}) = p_1(x'_{1,i})p_2(x'_{2,j})\Delta x_1 \Delta x_2 \tag{33}$$

Both Eqs. (32) and (33) need to be implemented for all combinations of $x'_{1,i}$ and $x'_{2,j}$ (i, j =1, 2, 3, …m). This will yields an $m\times m$ matrix of z and an $m\times m$ matrix of the associated probability P. The results need to be manipulated to obtain the PDF of Z or the exceedance probability (EP) of Z against a specified value. To obtain the PDF of Z, the range of z is divided into a number of intervals of Δz. Then, according to the proposition, the PDF of Z is estimated as

$$p(z_i) = \frac{1}{\Delta z}\sum_k P\left[(z_k - \frac{\Delta z}{2}) \le z_i < (z_k + \frac{\Delta z}{2})\right] \tag{34}$$

where $z_k = z_{i,j}$.

The EP of Z against a specified value z_s is estimated as

$$\mathrm{EP}(z_s) = \sum_k P(z_k > z_s) = \sum_{i=1}^{m}\sum_{j=1}^{m} P(z_{i,j} > z_s) \tag{35}$$

A two-dimensional PDS can be easily implemented using an Excel spreadsheet. A high-dimensional (n>2) PDS may require a computer program.

For the case study example considered in section 6 with the PDS, $\mathbf{X} = (X_A, X_B)$, and $Z = f(X_A, X_B) = \Delta X = X_B - X_A$. It is a two-dimensional problem.

In addition, it should be mentioned that the PDS algorithm naturally complies with the discretized formula of the Bayesian method (Huang 2022). The Markov Chain Monte Carlo (MCMC) sampling is often employed to generate Bayesian posterior distributions. However, the MCMC method in general associates with computational difficulty and lack of transparency. PDS might be an effective alternative to the MCMC method.

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